

# Announcements

- 1) Job talk Thursday,  
time TBA
- 2) Midterm week  
after the week  
after spring  
break

Recall: goal is to

triangularize a  
matrix by applying  
unitaries.

For a general matrix

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Start with  $A \in \mathbb{C}^{m \times n}$ .

Multiply  $A$  on the left  
by a unitary  $Q_1$ ,

where  $Q_1$  sends the  
first column of  $A$  to

$$\begin{bmatrix} x \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \text{ with } \|x\| = \|a_1\|_2$$

if  $a_1 = 1^{\text{st}}$  column of  $A$ .

Then apply

$$Q_2 = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & F_2 \\ \vdots & & & \\ 0 & & & \end{bmatrix}$$

where  $F_2$  sends the second column of  $Q, A$  (minus the first row), a vector called  $b$ , to

$\underbrace{\begin{bmatrix} y \\ 0 \\ \vdots \\ 0 \end{bmatrix}}_{m-1 \text{ spots}}$  with  $\|y\| = \|b\|_2$

$Q_3$  will act on  $Q_2 Q_1 A$

to produce

$$\begin{bmatrix} z \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \left. \right\}^{m-2 \text{ spots}}$$

on the third column, etc.

After applying  $Q_1, Q_2, \dots, Q_n$

to  $A$  in succession, we

obtain an upper-triangular

matrix  $R$ .

Then

$$R = (Q_n Q_{n-1} \cdots Q_3 Q_2 Q_1) A$$

$\underbrace{\hspace{10em}}_{Q^*}$

Since the product of unitaries  
is unitary,

$$\boxed{A = QR}$$

In our example from  
last class:

A was  $3 \times 3$ , but . . .

the first column had

a zero in it, which

reduced the calculation

of  $\odot$ , to 2 dimensions.

In general, we  
want to send

$a_1 = 1^{\text{st}}$  column of A

to  $\|a_1\|_2 e_1 \in \mathbb{C}^m$ .

$m=3$ , the orthogonal  
complement to any  
nonzero vector is now a  
plane. Not as easy  
as a line!

But - we are reflecting  
about a hyperplane  
Orthogonal to the  
vector  $a_1 - \|a_1\|_2 e_1$ .

If we call this vector  
 $v_i$ , then

$$P_i = \frac{v_i v_i^*}{\|v_i\|^2}$$

$$= \frac{v_i v_i^*}{v_i^* v_i}$$

is the orthogonal projection onto  
 $\text{Span}(v_i)$ .

The projection onto  
the hyperplane is

then  $\overline{I_m - P_1}$ ,

and we can obtain

$$Q_1 = 2(I_m - P_1) - I_m$$

$$= \overline{I_m - 2P_1}$$

Then continuing  
on in this fashion,

$$Q_2 = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ \vdots & & & \\ 0 & & F_2 & \end{bmatrix}$$

where  $F_2$  is the  
unitary  $\overline{I_{m-1}} - 2P_2$

where  $P_2$  is the rank  
one projection determined  
by the second column of  
 $Q_1 A$  (minus 1<sup>st</sup> row)

$$\text{Here } P_2 = V_2 V_2^* / V_2^* V_2$$

where, if  $b$  is the second column,

$$V_2 = b - \|b\|_2 e_1 \in \boxed{\mathbb{C}^{m-1}}$$

In general,

$$Q_j = \begin{bmatrix} I_{j-1} - O - \\ | \\ O \\ | \\ I_{m-j+1} - 2P_j \\ F_j \end{bmatrix}$$

where  $P_j = V_j V_j^* / V_j^* V_j$

Then

$$R = (Q_n Q_{n-1} \cdots Q_3 Q_2 Q_1) A$$

$\underbrace{\hspace{10em}}_{Q^*}$

Since the product of unitaries  
is unitary,

$$\boxed{A = QR}$$

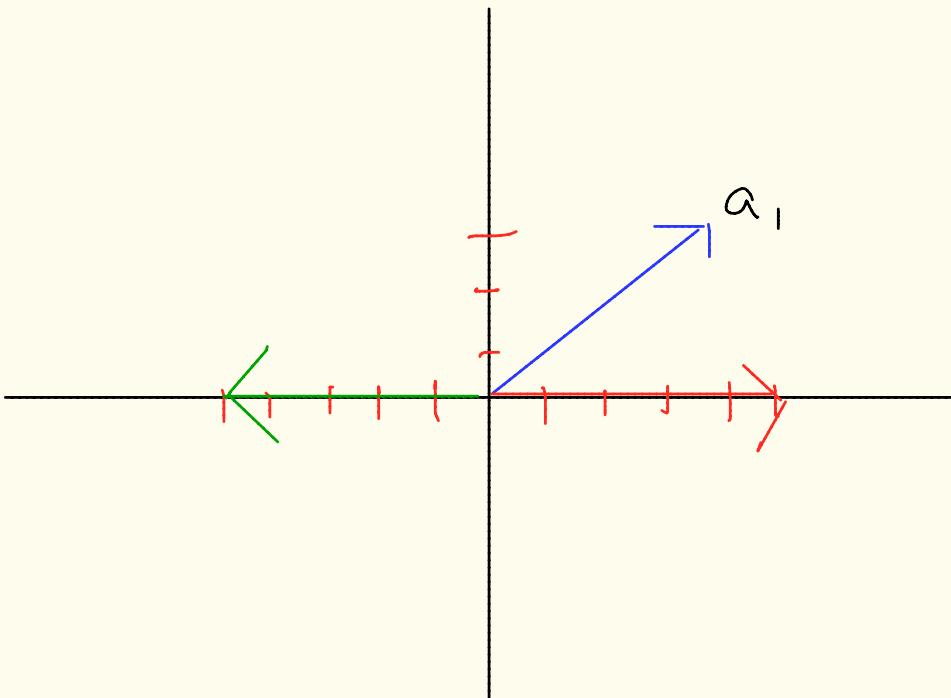
Definition: (Householder reflection)

The matrices  $F_i$   
generated by the algorithm  
for  $1 \leq i \leq n$  are called  
Householder reflections.

In general, if  $P$  is  
the orthogonal projection  
onto a one-dimensional  
subspace of  $\mathbb{C}^m$ ,  $I_m - 2P$   
is a Householder reflection.

## Choice of Signs

In our example, we had



We could have chosen the green vector instead of the red to map onto  $\mathcal{V}$  via  $Q_1$ . The "right" choice for numerical stability is the green vector! In general, we want to choose the vector "farther away" from  $x$  to prevent rounding errors.

Instead of

$$v_1 = a_1 - \|a_1\|_2 e_1,$$

we let

$$v_1 = a_1 - \text{sign}(a_{1,1}) \|a_1\|_2 e_1$$

where  $a_{1,1} = 1^{\text{st}}$   
coordinate of  $a_1$ .

Do this at every stage  
of the algorithm.